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NATO Advanced Study Institute
on Waveguide Optoelectronics

Glasgow, 1990

②
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DESIGN AND MODELLING OF PASSIVE AND ACTIVE
OPTICAL WAVEGUIDE DEVICES

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OUTLINE

① MODES IN WAVEGUIDES

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② LONGITUDINALLY VARIABLE STRUCTURES

③ COUPLED MODE THEORY

- COUPLERS
- STRUCTURES WITH GRATINGS

④ COUPLING LIGHT INTO WAVEGUIDES

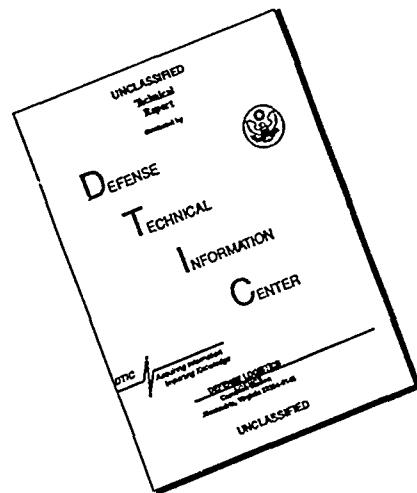
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⑤ WAVEGUIDES IN LASER CAVITIES

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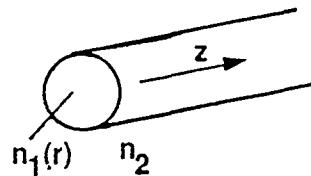
⑥ SOME GENERALITIES ABOUT WAVEGUIDE
MODELING AND DESIGN

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WAVE PROPAGATION MODEL DEFINITION OF PROBLEM



$$\nabla \times \bar{E} = -\frac{\partial \bar{B}}{\partial t} \quad \nabla \times \bar{H} = \frac{\partial \bar{D}}{\partial t}$$

$$\nabla \cdot \bar{D} = 0 \quad \nabla \cdot \bar{B} = 0$$

$$\bar{D} = \epsilon_0 n^2 \bar{E} \quad \bar{B} = \mu_0 \bar{H}$$

Find solutions of the form (modes) :

$$\bar{E} = \bar{E}(r, \phi) \exp[j(\omega t - \beta z)]$$

$$\bar{H} = \bar{H}(r, \phi) \exp[j(\omega t - \beta z)]$$

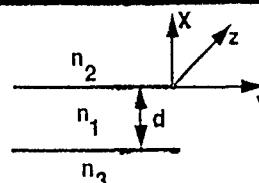
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WAVE PROPAGATION MODEL SLAB WAVEGUIDE

Two independent sets of solutions :

$$E_y, H_x, H_z \quad (\text{TE})$$

$$H_y, E_x, E_z \quad (\text{TM})$$



$$\text{TE : } \frac{d^2 E_y}{dx^2} + (n^2 k^2 - \beta^2) E_y = 0 \quad (k = \frac{\omega}{c})$$

$$\left\{ \begin{array}{ll} E_y = A e^{-\delta x} & x \geq 0 \\ E_y = A \cos \kappa x + B \sin \kappa x & 0 \leq x \leq d \\ E_y = (A \cos \kappa d - B \sin \kappa d) e^{\gamma(x+d)} & x \leq -d \end{array} \right.$$

$$\text{with } \delta = \sqrt{\beta^2 - n_2^2 k^2} \quad \kappa = \sqrt{n_1^2 k^2 - \beta^2} \quad \gamma = \sqrt{\beta^2 - n_3^2 k^2}$$

WAVE PROPAGATION MODEL SLAB WAVEGUIDE

Continuity of E_y and H_z ($\sim \frac{\partial E_y}{\partial x}$) at interfaces

→ eigenvalue equation

$$\operatorname{tg} \kappa d = \frac{\chi_x(\gamma + \delta)}{\kappa^2 - \gamma \delta} \rightarrow \text{discrete number of solutions for } \beta$$

$$\rightarrow \beta(\lambda, n_1, n_2, n_3, d)$$

WAVE PROPAGATION MODEL SLAB WAVEGUIDE

NORMALISATION

Waveguide characterized by

$$v = k_0 d \sqrt{n_1^2 - n_2^2}$$

v-number
(normalized frequency or thickness)

$$a = \frac{n_2^2 - n_3^2}{n_1^2 - n_2^2}$$

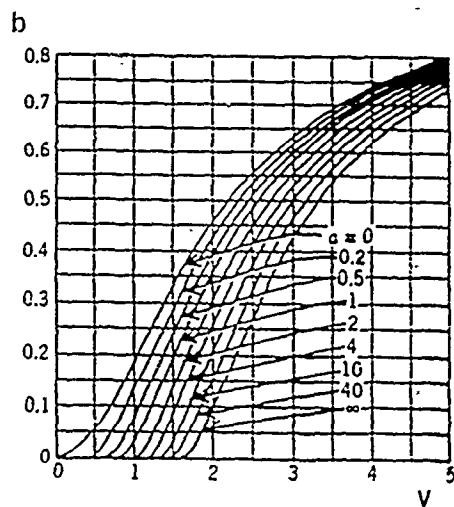
asymmetry factor

Mode characterized by

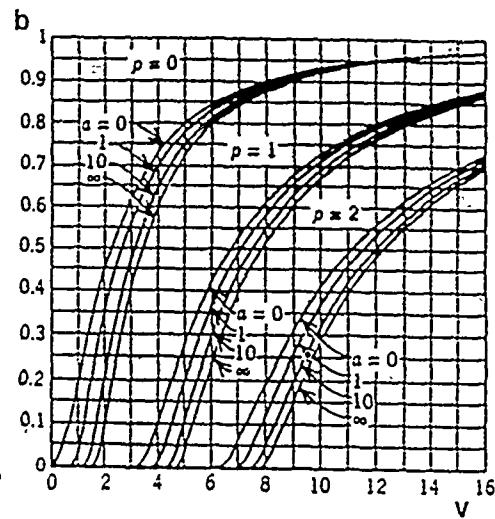
$$\beta = k_0 n_{\text{eff}}$$

$$b = \frac{n_{\text{eff}}^2 - n_2^2}{n_1^2 - n_2^2}$$

WAVE PROPAGATION MODEL SLAB WAVEGUIDE



FUNDAMENTAL TE MODE



3 LOWEST ORDER TE MODES

CONFINEMENT FACTOR Γ

$$\Gamma = \frac{\int_{\text{core}} |\psi|^2 dx}{\int_{-\infty} |\psi|^2 dx}$$

If the core layer shows gain g [cm⁻¹]
then the modal gain is Γ_g

$$n(x, y) = n_0(x) + \Delta n(x, y)$$

$$\nabla_T^2 E_y + (k_0^2 n^2(x, y) - \beta^2) \Xi_y = 0$$

Assumption: $\Xi_y(x, y) = F(x, y), G(y)$ where fast variations along y are taken up in $G(y)$

$$\rightarrow \frac{\partial F}{\partial y} = 0$$

$$\rightarrow \underbrace{\frac{1}{G} \frac{d^2 G}{dy^2}}_{\text{function of } y} + \underbrace{\frac{1}{F} \frac{\partial^2 F}{\partial x^2} + k_0^2 n^2 - \beta^2}_{\text{function of } x \text{ and } y} = 0$$

$$\rightarrow \frac{1}{F} \frac{\partial^2 F}{\partial x^2} + k_0^2 n^2 = f^2(y)$$

$$\frac{1}{G} \frac{d^2 G}{dy^2} - \beta^2 = -f^2(y)$$

$$f \triangleq k_0 n_{\text{eff}}(y)$$

Approximation of $n_{\text{eff}}(y)$ by perturbation method

$$n(x, y) = n_0(x) + \Delta n(x, y)$$

$$F_0(x) \text{ satisfies: } \frac{d^2 F_0}{dx^2} + k_0^2 (n_0^2 - n_{\text{eff},0}^2) F_0 = 0 \quad (1)$$

$$F(x, y) \text{ satisfies: } \frac{\partial^2 F}{\partial x^2} + k_0^2 (n^2 - n_{\text{eff}}^2) F = 0 \quad (2)$$

$$n^2 \approx n_0^2 + 2 \Delta n n_0$$

$$\int_{x-\text{axis}} (1) F - (2) F_0 \rightarrow (n_{\text{eff}}^2(y) - n_{\text{eff},0}^2) \int_{-\infty}^y F_0 F dx = \int_{-\infty}^y 2 \Delta n n_0 F F_0 dx$$

$$\rightarrow n_{\text{eff}}^2(y) = n_{\text{eff},0}^2 + \frac{\int_{-\infty}^y 2 \Delta n n_0 F F_0 dx}{\int_{-\infty}^y F_0 F dx}$$

$$\approx n_{\text{eff},0}^2 + 2 \frac{\int_{-\infty}^y \Delta n n_0 F_0^2 dx}{\int_{-\infty}^y F_0^2 dx}$$

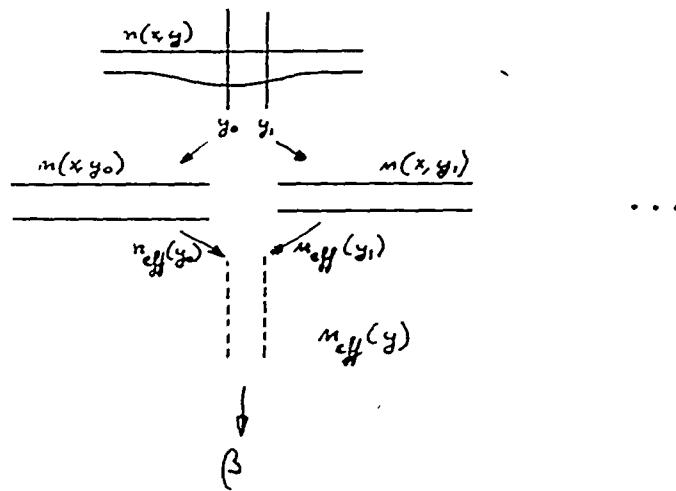
EFFECTIVE INDEX METHOD

w6

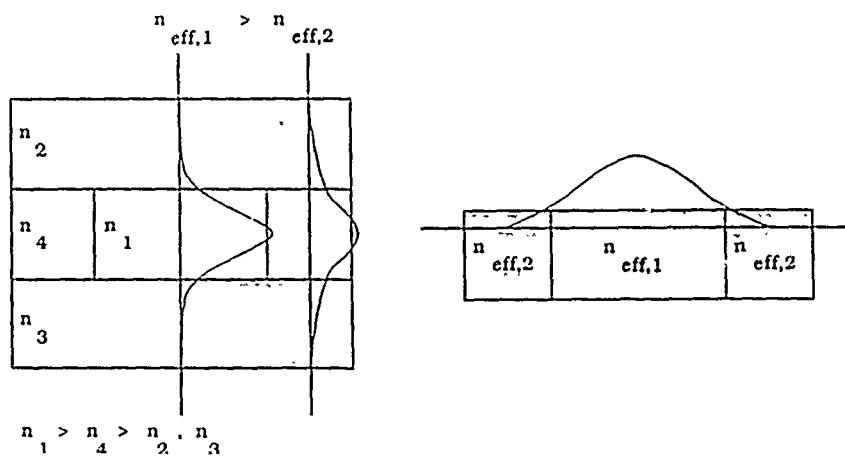
$$\rightarrow \begin{cases} \frac{\partial^2 F}{\partial x^2} + (k_0^2 n^2(x, y) - k_0^2 n_{eff}^2(y)) F = 0 \\ \frac{d^2 G}{dy^2} + (k_0^2 n_{eff}^2(y) - \beta^2) G = 0 \end{cases}$$

1D wave equation
(to be solved for each y)

1D wave equation
(to be solved once)

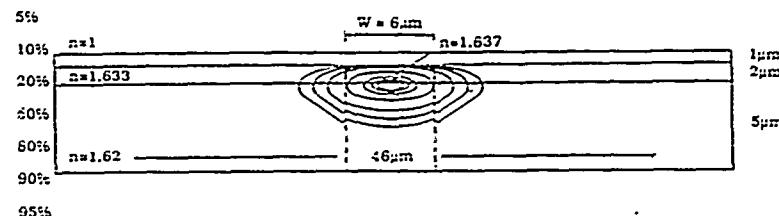


EFFECTIVE INDEX METHOD

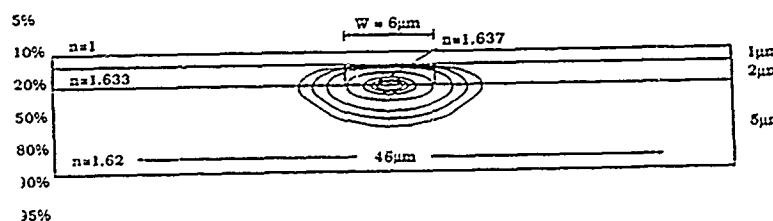


FUNDAMENTAL WAVEGUIDE MODE

A. EFFECTIVE INDEX METHOD



B. FINITE DIFFERENCE METHOD



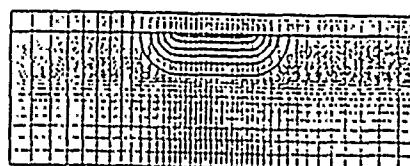
FINITE DIFFERENCE METHOD

BASIC EQUATION:

$$\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + (k_0^2 \epsilon_r - \beta^2) \phi = 0 \quad (1)$$

* A finite cross section is defined by enclosing the guide in a rectangular box, where $\phi = 0$ on the side walls

* In this box a graded mesh is defined



FINITE DIFFERENCE METHOD

Continuity conditions :

$$\left. \begin{array}{l} \phi \\ \frac{\partial \phi}{\partial n} \end{array} \right\} \text{continuous at boundary between } S_v$$

Substitution of the discretized form of $\nabla^2 \phi$ and the continuity conditions into (1) leads to :

$$\begin{aligned} & \frac{2}{w(e+w)} \phi_w + \frac{2}{s(n+s)} \phi_s - \left(\frac{2}{w(e+w)} + \frac{2}{e(e+w)} + \frac{2}{s(n+s)} \right. \\ & \left. \frac{2}{n(n+s)} \right) \phi_P + \frac{2}{e(e+w)} \phi_E + \frac{2}{n(n+s)} \phi_N \\ & + k_0^2 \frac{wn\varepsilon_1 + ws\varepsilon_2 + es\varepsilon_3 + en\varepsilon_4}{(e+w)(n+s)} \phi_P - \beta^2 \phi_P = 0 \end{aligned} \quad (5)$$

FINITE DIFFERENCE METHOD

Equation (5) holds for each node point P. The resultant eigenvalue equation is of the form

$$[[A] - \beta^2 [U]] [X] = 0 \quad (6)$$

with

$$[X] = [\phi_1, \phi_2, \dots, \phi_{NTOT}]^T \quad (7)$$

[U] is the unit matrix, and NTOT is the total number of mesh points. The matrix [A] is a real, but generally not symmetric, sparse matrix. Eigenvalues and corresponding eigenvectors of [A] are found by a simultaneous iteration algorithm.

BEAM PROPAGATION METHOD TWO DIMENSIONAL

Problem :

Calculation of the propagation of a given input field $E_0(x,z)$ through a medium with a refractive index $n(x,z)$

Assumptions :

1. Scalar wave equation

$$\nabla^2 E + k^2 n^2(x,z)E = 0 \quad (1)$$

BEAM PROPAGATION METHOD TWO DIMENSIONAL

2. Refractive index variation can be written as :

$$n(x,z) = n_0(x) + \Delta n(x,z) \quad (2)$$

where $\Delta n \ll n_0$ and $n_0(x)$ chosen so that the solutions of :

$$\nabla^2 \Phi + k^2 n_0^2(x)\Phi = 0 \quad (3)$$

are known eigenfunctions :

$$\Phi_n(x) e^{-ik_n z} \quad (4)$$

In practice. $n_0 = \text{constant}$

BEAM PROPAGATION METHOD TWO DIMENSIONAL

3. Neglect the influence of the reflected fields on the forward propagating beam :

- no large abrupt change of $n(x,z)$ as a function of z
- no periodic reflections that add up coherently

This assumption yields for a field $\varepsilon(x,z)$ propagating in n_0

$$\varepsilon = \sum_{n=1}^{\infty} B_n \Phi_n e^{ik n z} \quad (5)$$

Boundary value problem transformed into an initial value problem
 \Rightarrow a stepwise solution feasible

4 Paraxial fields

BEAM PROPAGATION METHOD TWO DIMENSIONAL

Assume

$$E(x, z_0 + \Delta z) = \varepsilon(x, z_0 + \Delta z) \cdot e^{\Gamma} \quad (7)$$

where

$$\varepsilon(x, z_0 + \Delta z)$$

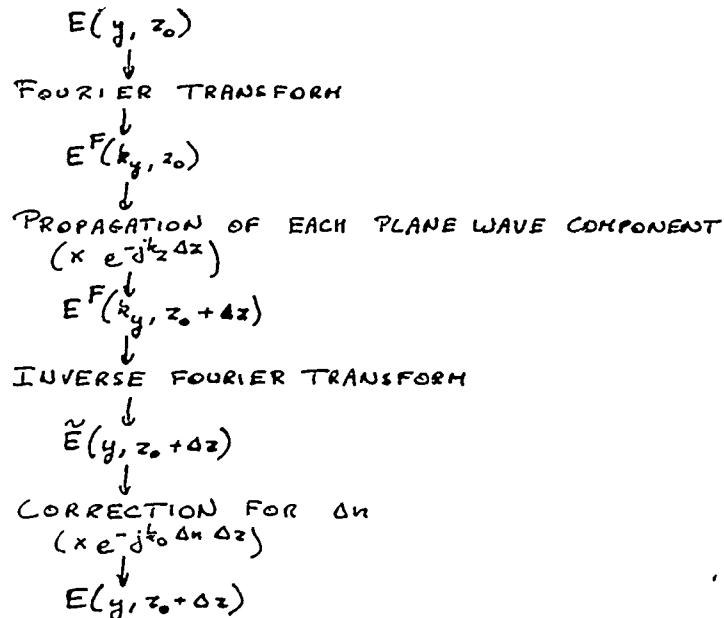
is propagated in the homogeneous medium n_0 ,
 e^{Γ} is a correction factor due to $\Delta n(x,z)$

$\varepsilon(x,z)$ satisfies

$$\nabla^2 \varepsilon + k^2 n_0^2 \varepsilon = 0 \quad (8)$$

BPM

ALGORITHM FOR ONE PROPAGATION STEP



BOUNDARY CONDITIONS

FFT is

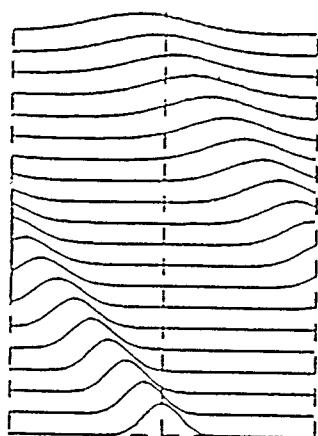
- discrete in both x and k_x space
- limited window in both dimensions

FFT is F.T. of the periodic extension of the field

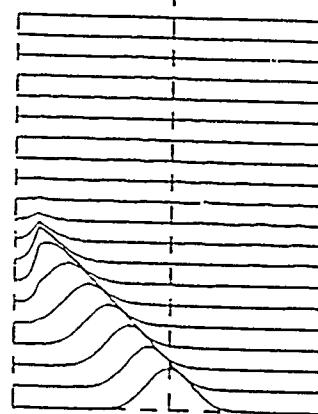
Radiation condition is simulated by absorbing region
at the edges.
(- windowing filter)

GAUSSIAN BEAM HOMOGENEOUS MEDIUM

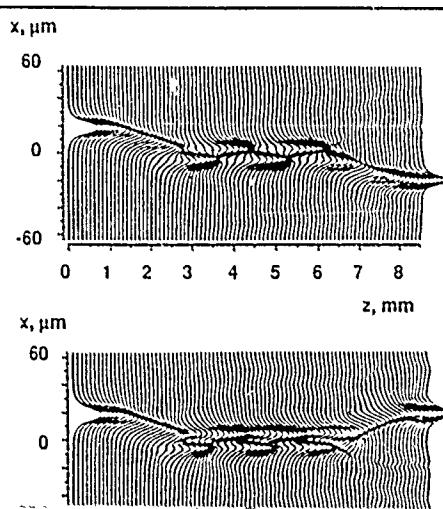
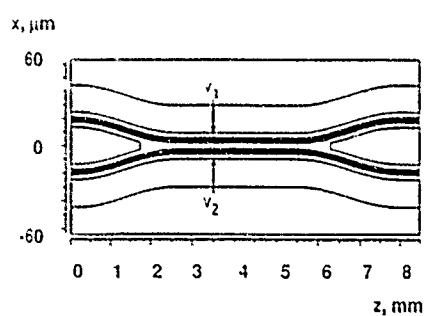
NO ABSORBER

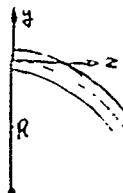


WITH ABSORBER



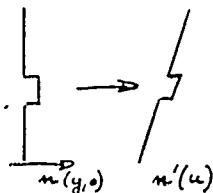
BPM EXAMPLE : DIRECTIONAL COUPLER



BENDS

conformal transformation : $w = u + jw = R \ln \frac{z+jz+R}{R}$

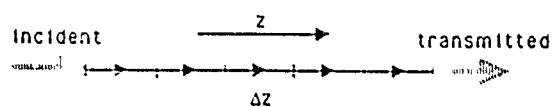
- waveguide in (u, v) plane is v -independent
- wave equation becomes new wave equation with $n'(u) = \exp(u/R) n(u)$
 $\approx \left(1 + \frac{u}{R}\right) n(u)$ for $u \ll R$



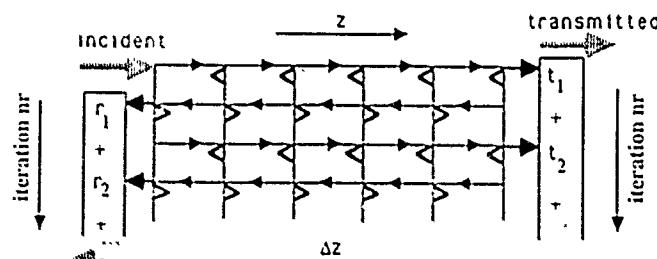
⇒ curved waveguide can be analysed as straight waveguide with modified refractive index profile

ITERATION PRINCIPLE OF THE UNIDIRECTIONAL & BIDIRECTIONAL BPM

UNIDIRECTIONAL BPM

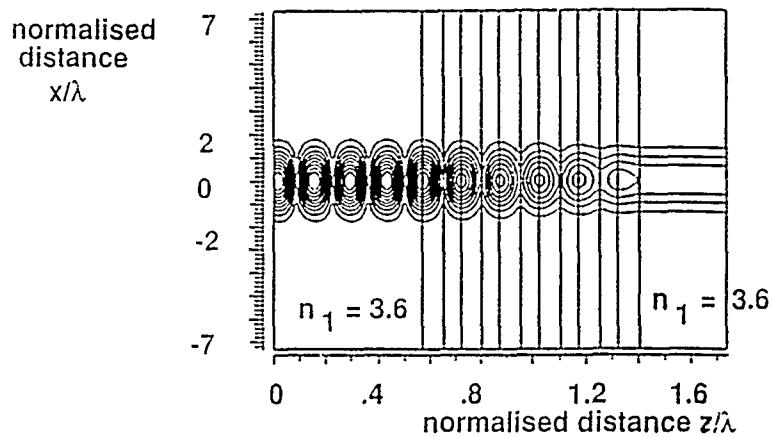


BIDIRECTIONAL BPM



REFLECTIONS OF A GAUSSIAN BEAM INCIDENT ON A BRAGG REFLECTOR

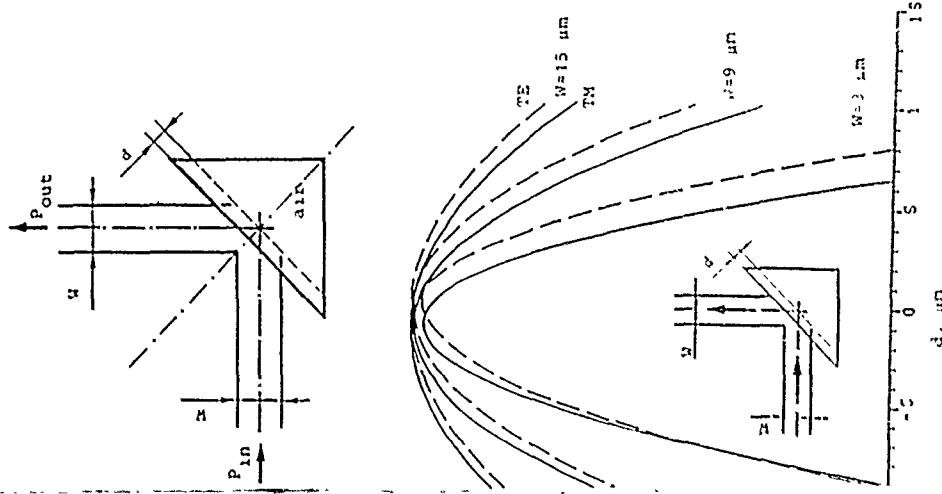
simulated by the bidirectional BPM at $\lambda = 0.864 \mu\text{m}$



- total field amplitude $|E(x,z)|$ is normalised to 1
- contour lines with interval 0.1 are plotted

BS AT 90° CORNER BENDS

BPM ANALYSIS



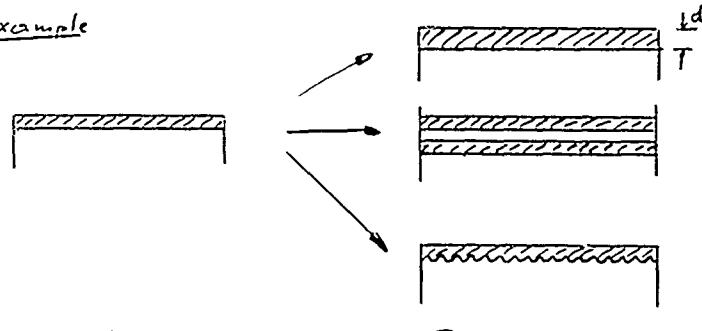
COUPLED MODE THEORY

W16

ANALYSIS OF DIELECTRIC STRUCTURE WHICH IS A PERTURBATION
OF A SIMPLER DIELECTRIC STRUCTURE

→ COUPLED MODE THEORY

Example



Unperturbed

Perturbed

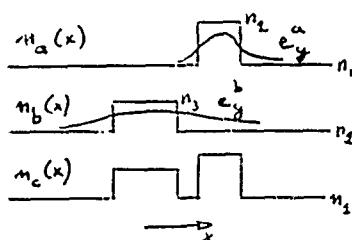
$$\Psi = \sum A_i \Psi_i$$

$$\Psi = \sum A_i(z) \Psi_i$$

$$A_i(z) ?$$

DIRECTIONAL COUPLER

W20



unperturbed waveguide "a"

unperturbed waveguide "b"

perturbed waveguide (both for "a" and "b")

$$E_y = A(z) e_y^a(x) e^{j(\omega t - \beta_a z)} + B(z) e_y^b(x) e^{j(\omega t - \beta_b z)}$$

P_{pert}^a

$$e^{j\omega t} \epsilon_0 e_y^a(x) A(z) [n_c^2 - n_a^2] e^{-j\beta_a z}$$

P_{pert}^b

$$e^{j\omega t} \epsilon_0 e_y^b(x) B(z) [n_c^2 - n_b^2] e^{-j\beta_b z}$$

$$\rightarrow \left| \frac{dA}{dz} e^{j(\omega t - \beta_a z)} \right| = \frac{j}{\omega} \frac{\partial}{\partial z} \int_{-\infty}^{\infty} [P_{\text{pert}}^a + P_{\text{pert}}^b] e_y^a(x) dx$$

DIRECTIONAL COUPLER

WL1

$$\begin{cases} \frac{dA}{dz} = -j K_{ab} B e^{+j(\beta_a - \beta_b)z} - j M_a A \\ \frac{dB}{dz} = -j K_{ba} A e^{j(\beta_b - \beta_a)z} - j M_b B \end{cases}$$

with

$$K_{ab} = \frac{\omega \epsilon_0}{4} \int_{-\infty}^{\infty} (n_c^2 - n_a^2) E_y^a E_y^b dx$$

$$M_a = \frac{\omega \epsilon_0}{4} \int_{-\infty}^{\infty} (n_c^2 - n_a^2) (E_y^a)^2 dx$$

Change of variables : $A = A' e^{-j M_a z}$ and $B = B' e^{-j M_b z}$

$$\begin{cases} \frac{dA'}{dz} = -j K_{ab} B' e^{j(\beta_a + M_a - \beta_b - M_b)z} \triangleq -j K_{ab} B' e^{2j\delta z} \\ \frac{dB'}{dz} = -j K_{ba} A' e^{j(\beta_b + M_b - \beta_a - M_a)z} \triangleq -j K_{ba} A' e^{-2j\delta z} \end{cases}$$

$$2\delta = \beta_a + M_a - \beta_b - M_b$$

DIRECTIONAL COUPLER

WL3

CASE 1 : $\delta = 0$

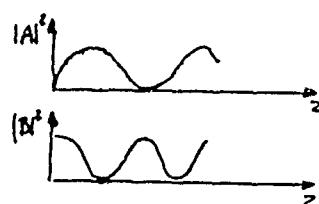
(symmetry)

$$K_{ab} = K_{ba} = \kappa$$

$$|A|^2 = P_0 \sin^2(kz)$$

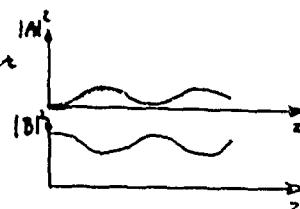
$$|B|^2 = P_0 \cos^2(kz)$$

$$\text{Power transfer length : } L = \frac{\pi}{2k}$$



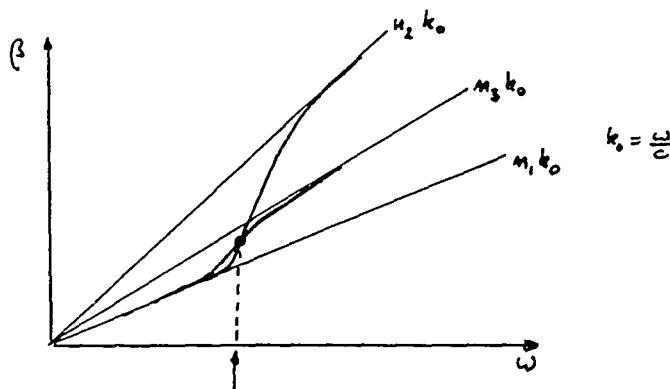
CASE 2: $\delta \neq 0 \rightarrow N_p$ complete power transfer

$$\frac{|A|_{\max}^2}{P_0} = \frac{|K_{ba}|^2}{K_{ba} K_{ab} + \delta^2}$$



DIRECTIONAL COUPLER

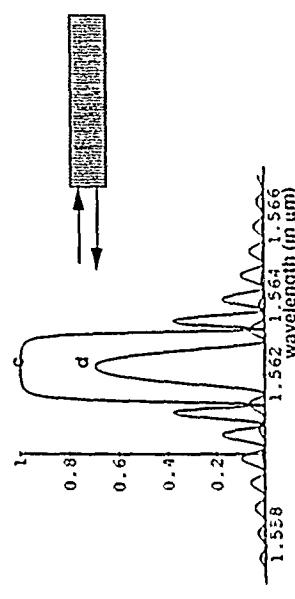
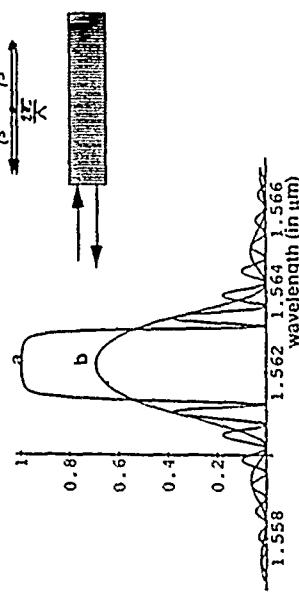
W24



Frequency where coupling is strong

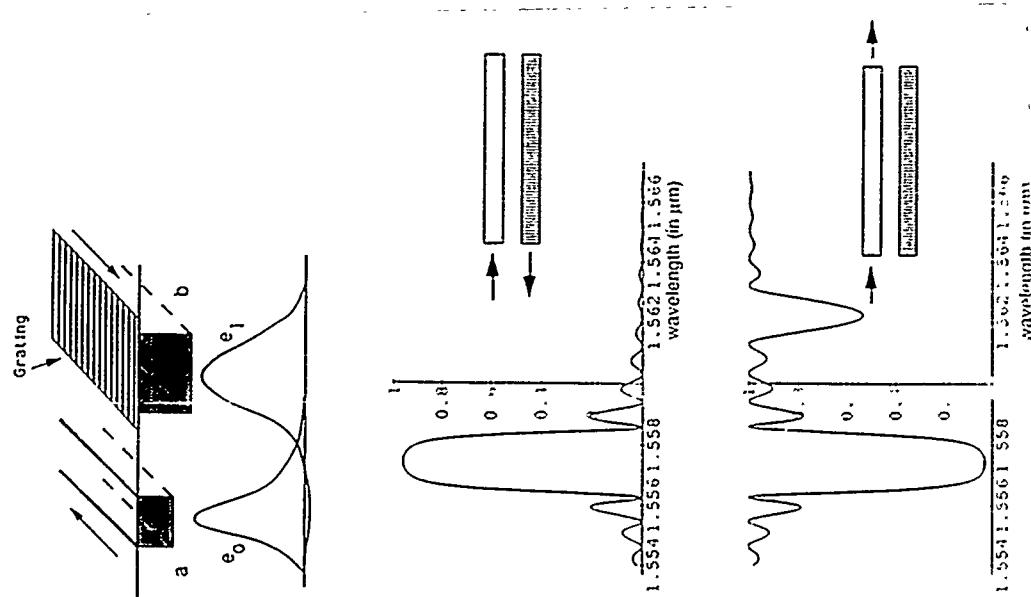
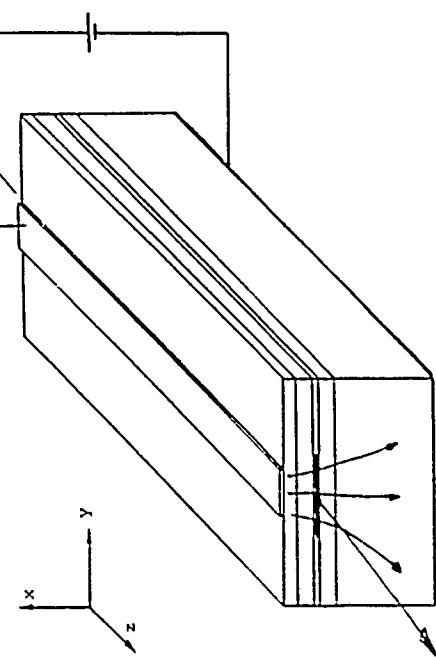
WAVEGUIDES WITH GRATINGS (BRAGG REFLECTORS) ANALYSED WITH COUPLED MODE THEORY

Strong coupling if $\beta - \frac{2\pi}{\lambda} = -\beta$



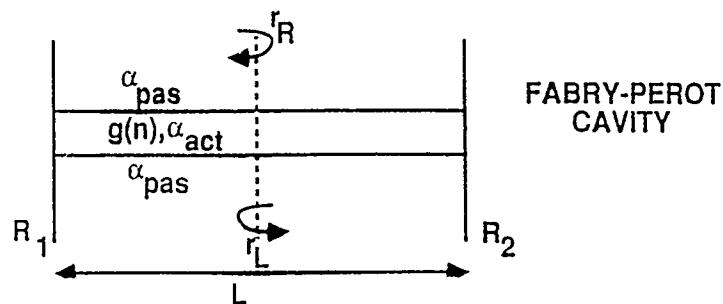
- a. $L = 80 \text{ cm}$, $R = 60 \text{ cm}$
- b. $L = 200 \text{ cm}$, $R = 60 \text{ cm}$
- c. $L = 600 \text{ cm}$, $R = 60 \text{ cm}$
- d. $L = 100 \text{ cm}$, $R = 60 \text{ cm}$

SEMICONDUCTOR LASER DIODES
Some basics



IMEC-RUG

LASER DIODES Cavity Resonance

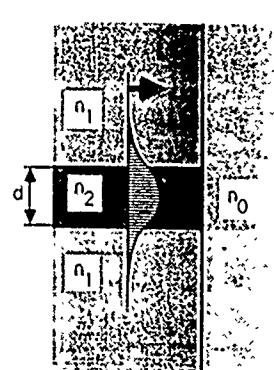
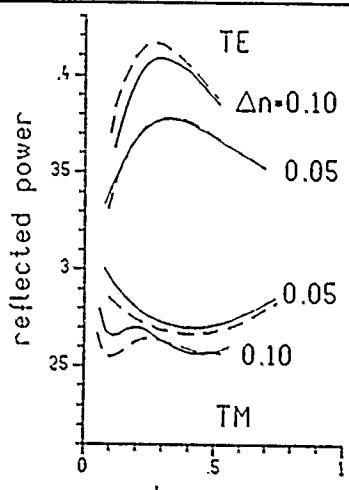


$$\text{RESONANCE} : \underline{r_L(n, \lambda) \cdot r_R(n, \lambda)} = 1 \quad \xrightarrow{\text{roundtrip gain}}$$

$$\text{FABRY-PEROT} : g(n) = \alpha + \frac{1}{2L} \ln \frac{1}{R_1 R_2} \text{ (amplitude)}$$

$$\frac{\lambda}{n_r} = \frac{2L}{m}, m \text{ integer (phase)}$$

BIDIRECTIONAL BPM : REFLECTION FROM A SEMICONDUCTOR LASER FACET

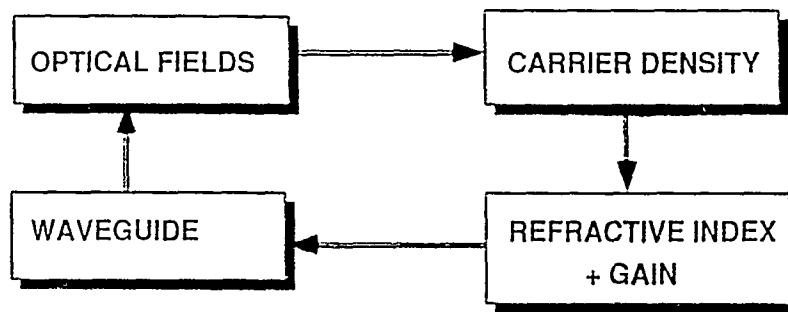


Laser facet configuration

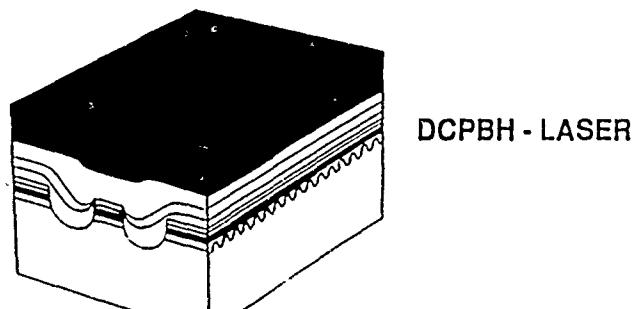
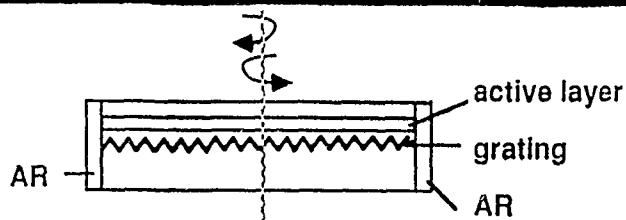
— bidirectional BPM
..... exact solution

SELF CONSISTENT MODELLING

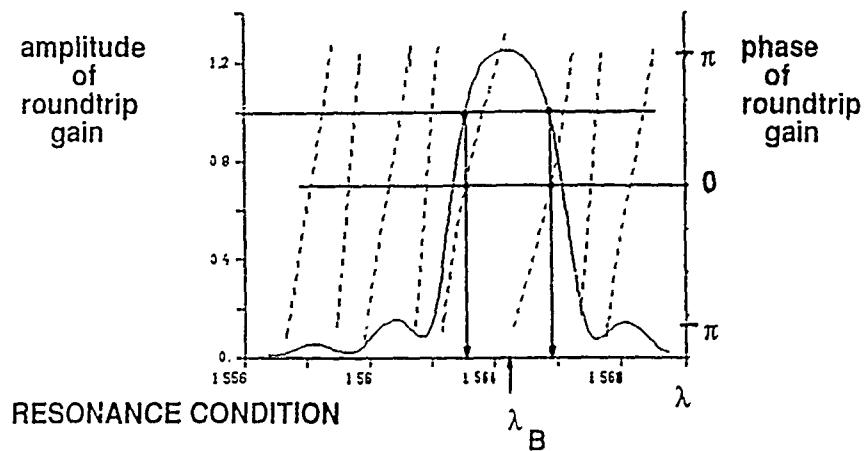
EXAMPLE : ELECTRICAL - OPTICAL INTERACTION



SLM LASERS DISTRIBUTED FEEDBACK (DFB) LASER



SLM LASERS DFB LASER



RESONANCE CONDITION

λ_B

PHASE :- no mode at λ_B

- modes symmetrically around λ_B

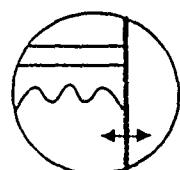
→ two lines in spectrum

SLM LASERS SINGLE MODE DFB LASERS

1. ONE OR TWO NON-AR-COATED FACETS

- ASYMMETRIC LASER
- 2 MODES DO NOT HAVE THE SAME THRESHOLD GAIN
- ONE LINE IN SPECTRUM

PROBLEM WITH FACETS IN DFB LASERS :

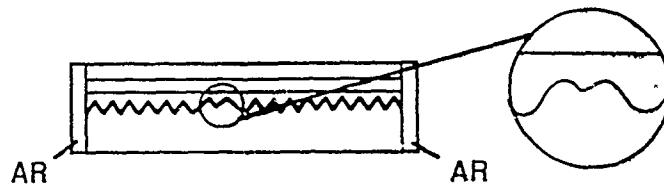


position of facets with respect to grating
can not be controlled technologically

- some lasers good, some bad
- yield problem

SLM LASERS SINGLE MODE DFB LASERS

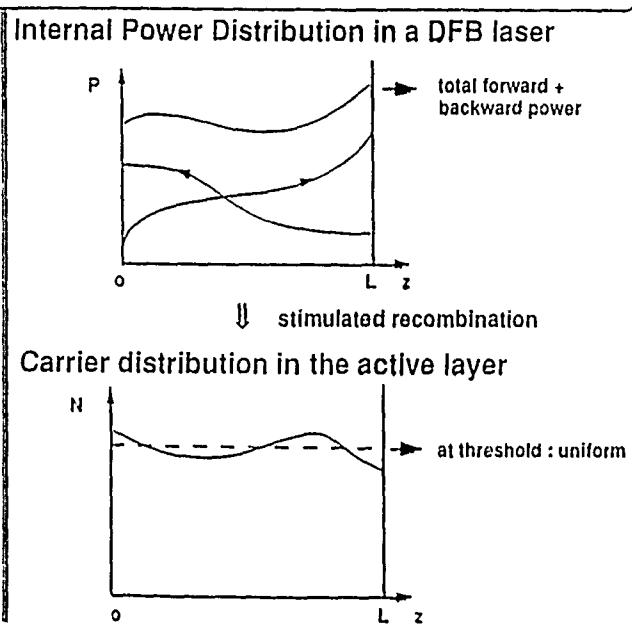
2. $\lambda/4$ PHASE SHIFTED LASERS



- PHASE RESONANCE AT λ_B
- ONE LASING PEAK AT λ_B

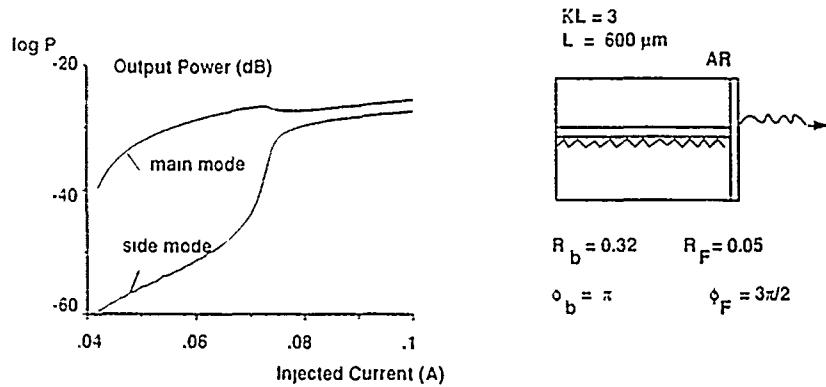
LONGITUDINAL SPATIAL HOLE BURNING

$P(z)$
 \Downarrow
 $N(z)$
 \Downarrow
 $\Delta n_r(z)$
 \Downarrow
 { Bragg Deviation
 \Downarrow
 $\frac{2\pi}{\lambda} n_{\text{eff}}(z) - \frac{\pi}{\Lambda}$



DC ANALYSIS OF DFB LASER

EXAMPLE : UNSTABLE SINGLE MODE BEHAVIOUR DUE TO SPATIAL HOLE BURNING

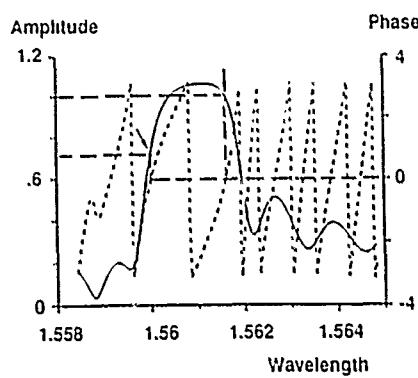


$$I_{th} = 39.56 \text{ mA}, \lambda_{th} = 1.5616, \Delta\alpha L = 0.25$$

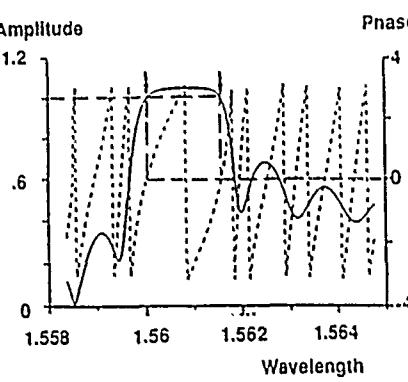
DC ANALYSIS OF DFB LASER

ROUNDTRIP GAIN OF UNSTABLE DFB LASER

At threshold main mode
 $I = 39.6 \text{ mA}$



At threshold side mode
 $I = 70 \text{ mA}$



SOME CHARACTERISTICS OF OPTICAL WAVEGUIDE MODELS

① Rigorous solution of a waveguide problem is difficult
↓

People introduce simplifications
BUT: Validity of simplifications not clearly established

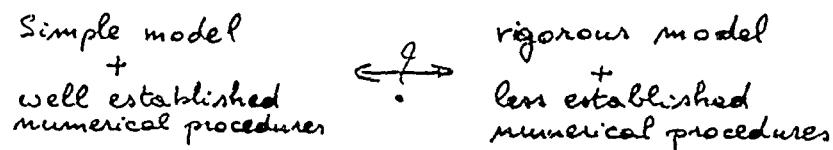
Simplifications very specific to specific structures
⇒ many different models

② Very few problems can be solved analytically
↓

Numerical solution methods

BUT:

- numerical solution does not easily allow for design and optimisation within certain parameter space
- numerical solution introduces numerical error
Validation ??



③ It is difficult to compare modelling results with experimental results quantitatively

Because :

- modelling result based on simplified model
- experimental structure not sufficiently well defined

④ All models are limited to single (or few) device level

No higher level "circuit-like" models available.

⑤ Most software implementations are produced by universities

- maintenance + servicing + updating ??

CONCLUSIONS

- Optical waveguide modelling requires simplification.
Care is needed to judge the appropriateness of the simplifications
- Modelling is good for
 - demonstrating conceptual ideas theoretically
 - explain experimental observations
 - it is inadequate for accurate design and optimisation

All evolution is needed towards integrated modelling and CAD-tools that contain a number of models with a flexible interface in between them and with sufficient intelligence to protect the user against use beyond the validity range of the models.